## Probabilistic clustering and the EM algorithm

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## Outline

(1) The EM algorithm for the Gaussian mixture model
(2) More examples of graphical models

K-means
Key assumption: Data composed of $K$ "roundish" clusters of similar sizes with centroids $\left(\boldsymbol{\mu}_{1}, \cdots, \boldsymbol{\mu}_{K}\right)$.

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## $K$-means algorithm

(1) Draw centroids at random
(2) Assign each point to the closest centroid

$$
C_{k} \leftarrow\left\{i \mid\left\|\mathbf{x}_{i}-\boldsymbol{\mu}_{k}\right\|^{2}=\min _{j}\left\|\mathbf{x}_{i}-\boldsymbol{\mu}_{j}\right\|^{2}\right\}
$$

(3) Recompute centroid as center of mass of the cluster
(1) Go to 2

$$
\boldsymbol{\mu}_{k} \leftarrow \frac{1}{\left|C_{k}\right|} \sum_{i \in C_{k}} \mathbf{x}_{i}
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- The algorithm however typically get stuck in local minima and it practice it is necessary to try several restarts of the algorithm with a random initialization to have chances to obtain a better solution.
- Will fail if the clusters are not round
- A good initialization for K-means is K-means++, (Arthur and Vassilvitskii, 2007), (included in all good libraries).

See Arthur, D. and Vassilvitskii, S. (2007). k-means++: the advantages of careful seeding. Proceedings of the 18 th annual ACM-SIAM symposium on Discrete algorithms.

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## The Gaussian mixture model and the EM algorithm

## Gaussian mixture model

- $K$ components
- $\boldsymbol{z}$ component indicator
- $\boldsymbol{z}=\left(z_{1}, \ldots, z_{K}\right)^{\top} \in\{0,1\}^{K}$
- $\boldsymbol{z} \sim \mathcal{M}\left(1,\left(\pi_{1}, \ldots, \pi_{K}\right)\right)$
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- $p(\mathbf{x})=\sum_{k=1}^{K} \pi_{k} \mathcal{N}\left(\mathbf{x} ; \boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}\right)$
- Estimation: $\underset{\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}}{\operatorname{argmax}} \log \left[\sum_{k=1}^{K} \pi_{k} \mathcal{N}\left(\mathbf{x} ; \boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}\right)\right]$


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- The marginal $\log$-likelihood $\tilde{\ell}(\theta)=\sum_{i} \log \left(p\left(\mathbf{x}^{(i)}\right)\right)$ with $\theta=\left(\boldsymbol{\pi},\left(\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}\right)_{1 \leq k \leq K}\right)$ is now complicated

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- Can we still use the intuitions above to construct an algorithm maximizing the marginal likelihood?

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\mathcal{L}(q, \boldsymbol{\theta})=\log p(\mathbf{x} ; \boldsymbol{\theta})-K L(q \| p(\cdot \mid \mathbf{x} ; \boldsymbol{\theta}))
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## Principle of the Expectation-Maximization Algorithm

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\log p(\mathbf{x} ; \boldsymbol{\theta})= & \log \sum_{\boldsymbol{z}} p(\mathbf{x}, \boldsymbol{z} ; \boldsymbol{\theta})=\log \sum_{\boldsymbol{z}} q(\boldsymbol{z}) \frac{p(\mathbf{x}, \boldsymbol{z} ; \boldsymbol{\theta})}{q(\boldsymbol{z})} \\
\geq & \sum_{\boldsymbol{z}} q(\boldsymbol{z}) \log \frac{p(\mathbf{x}, \boldsymbol{z} ; \boldsymbol{\theta})}{q(\boldsymbol{z})} \\
& =\mathbb{E}_{q}[\log p(\mathbf{x}, \boldsymbol{z} ; \boldsymbol{\theta})]+H(q)=: \mathcal{L}(q, \boldsymbol{\theta})
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${ }^{a}$ If the complete log-likelihood is a canonical exponential family.

## A graphical idea of the EM algorithm



Expectation Maximization algorithm

Expectation step


Maximization step

$$
\begin{aligned}
\boldsymbol{\theta}^{\mathrm{old}} & =\boldsymbol{\theta}^{(t-1)} \\
\boldsymbol{\theta}^{\text {new }} & =\boldsymbol{\theta}^{(t)}
\end{aligned}
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(1) $q(\boldsymbol{z})=p\left(\boldsymbol{z} \mid \mathbf{x} ; \boldsymbol{\theta}^{(t-1)}\right)$


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(1) $\boldsymbol{\theta}^{(t)}=\underset{\boldsymbol{\theta}}{\operatorname{argmax}} \mathbb{E}_{q}[\log p(\mathbf{x}, \boldsymbol{z} ; \boldsymbol{\theta})]$

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$$

## Expectation Maximization algorithm

Initialize $\boldsymbol{\theta}=\boldsymbol{\theta}_{0}$
WHILE (Not converged)
Expectation step
(1) $q(\boldsymbol{z})=p\left(\boldsymbol{z} \mid \mathbf{x} ; \boldsymbol{\theta}^{(t-1)}\right)$
(2) $\mathcal{L}(q, \boldsymbol{\theta})=\mathbb{E}_{q}[\log p(\mathbf{x}, \boldsymbol{z} ; \boldsymbol{\theta})]+H(q)$


Maximization step
(1) $\boldsymbol{\theta}^{(t)}=\underset{\boldsymbol{\theta}}{\operatorname{argmax}} \mathbb{E}_{q}[\log p(\mathbf{x}, \boldsymbol{z} ; \boldsymbol{\theta})]$

ENDWHILE

## Expected complete log-likelihood

With the notation: $q_{i k}^{(t)}=\mathbb{P}_{q_{i}^{(t)}}\left(z_{k}^{(i)}=1\right)=\mathbb{E}_{q_{i}^{(t)}}\left[z_{k}^{(i)}\right]$, we have

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## Expectation step for the Gaussian mixture

We computed previously $q_{i}^{(t)}\left(\boldsymbol{z}^{(i)}\right)$, which is a multinomial distribution defined by

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Abusing notation we will denote $\left(q_{i 1}^{(t)}, \ldots, q_{i K}^{(t)}\right)$ the corresponding vector of probabilities defined by

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$$
\begin{gathered}
q_{i k}^{(t)}=\mathbb{P}_{q_{i}^{(t)}}\left(z_{k}^{(i)}=1\right)=\mathbb{E}_{q_{i}^{(t)}}\left[z_{k}^{(i)}\right] \\
q_{i k}^{(t)}=p\left(z_{k}^{(i)}=1 \mid \mathbf{x}^{(i)} ; \boldsymbol{\theta}^{(t-1)}\right)=\frac{\pi_{k}^{(t-1)} \mathcal{N}\left(\mathbf{x}^{(i)}, \boldsymbol{\mu}_{k}^{(t-1)}, \boldsymbol{\Sigma}_{k}^{(t-1)}\right)}{\sum_{j=1}^{K} \pi_{j}^{(t-1)} \mathcal{N}\left(\mathbf{x}^{(i)}, \boldsymbol{\mu}_{j}^{(t-1)}, \boldsymbol{\Sigma}_{j}^{(t-1)}\right)}
\end{gathered}
$$

Maximization step for the Gaussian mixture

$$
\left(\boldsymbol{\pi}^{t},\left(\boldsymbol{\mu}_{k}^{(t)}, \boldsymbol{\Sigma}_{k}^{(t)}\right)_{1 \leq k \leq K}\right)=\underset{\boldsymbol{\theta}}{\operatorname{argmax}} \mathbb{E}_{q^{(t)}}[\tilde{\ell}(\boldsymbol{\theta})]
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$$

This yields the updates:

$$
\begin{gathered}
\boldsymbol{\mu}_{k}^{(t)}=\frac{\sum_{i} \mathbf{x}^{(i)} q_{i k}^{(t)}}{\sum_{i} q_{i k}^{(t)}}, \quad \boldsymbol{\Sigma}_{k}^{(t)}=\frac{\sum_{i}\left(\mathbf{x}^{(i)}-\boldsymbol{\mu}_{k}^{(t)}\right)\left(\mathbf{x}^{(i)}-\boldsymbol{\mu}_{k}^{(t)}\right)^{\top} q_{i k}^{(t)}}{\sum_{i} q_{i k}^{(t)}} \\
\text { and } \quad \pi_{k}^{(t)}=\frac{\sum_{i} q_{i k}^{(t)}}{\sum_{i, k^{\prime}} q_{i k^{\prime}}^{(t)}}
\end{gathered}
$$

Final EM algorithm for the Multinomial mixture model
Initialize $\boldsymbol{\theta}=\boldsymbol{\theta}_{0}$
WHILE (Not converged)
Expectation step

$$
q_{i k}^{(t)} \leftarrow \frac{\pi_{k}^{(t-1)} \mathcal{N}\left(\mathbf{x}^{(i)}, \boldsymbol{\mu}_{k}^{(t-1)}, \mathbf{\Sigma}_{k}^{(t-1)}\right)}{\sum_{j=1}^{K} \pi_{j}^{(t-1)} \mathcal{N}\left(\mathbf{x}^{(i)}, \boldsymbol{\mu}_{j}^{(t-1)}, \mathbf{\Sigma}_{j}^{(t-1)}\right)}
$$

Maximization step

$$
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\end{gathered}
$$

ENDWHILE

EM Algorithm for the Gaussian mixture model III

$$
p(\mathbf{x} \mid \boldsymbol{z})
$$

$$
p(\boldsymbol{z} \mid \mathbf{x})
$$



## Outline

## (1) The EM algorithm for the Gaussian mixture model

(2) More examples of graphical models

## Factorial Analysis



- $\Lambda \in \mathbb{R}^{d \times k}$ is the matrix of factors or principal directions


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- $\Lambda \in \mathbb{R}^{d \times k}$ is the matrix of factors or principal directions
- $Z_{i} \in \mathbb{R}^{k}$ are the loadings or principal components

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X_{i}=\Lambda Z_{i}+\varepsilon_{i} \quad \text { with } \quad \varepsilon_{i} \sim \mathcal{N}(0, \Psi) .
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The model essentially retrieves Principal Component Analysis for $\Psi=\sigma^{2} I_{d}$.

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$\Lambda$ can be learned (up to a rotation on the right) together with $\Psi$ using an EM algorithm, where $Z$ is treated as a latent variable.

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- Possible to model non-isotropic noise


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- By changing the distributions on $Z_{i}$ and $X_{i}$, we can design variant of PCA more suitable for different type of data: Multinomial PCA, Poisson PCA, etc.
- Can be inserted in a mixture of Gaussians model to help model Gaussians in high dimension.


## Latent Dirichlet Allocation as Multinomial PCA

Replacing

- the distribution on $Z_{i}$ by a Dirichlet distribution
- the distribution of $X_{i}$ by a Multinomial


## Latent Dirichlet Allocation as Multinomial PCA

Replacing

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- the distribution of $X_{i}$ by a Multinomial

- Topic proportions for document $i$ : $\boldsymbol{\theta}_{i} \in \mathbb{R}^{K}$

$$
\boldsymbol{\theta}_{i} \sim \operatorname{Dir}(\boldsymbol{\alpha})
$$

- Empirical words counts for document $i$ : $\mathbf{x}_{i} \in \mathbb{R}^{d}$

$$
\mathbf{x}_{i} \sim \mathcal{M}\left(N_{i}, \mathbf{B} \boldsymbol{\theta}_{i}\right)
$$

## Temporal models

Hidden Markov Model and Kalman Filter


## Temporal models

Hidden Markov Model and Kalman Filter


Conditional Random Field (chain case)


- A structured version of logistic regression where the output is a sequence.


## More temporal models

Second order auto-regressive model with latent switching state


## More temporal models

Second order auto-regressive model with latent switching state


Factorial Hidden Markov models (Ghahramani and Jordan, 1996)


## Restricted Boltzman Machines (Smolensky, 1986)



$$
P(Y, Z)=\exp \left(\langle Y, \theta\rangle+Z^{\top} W Y+\langle Z, \eta\rangle-A(\theta, W, \eta)\right)
$$

- $p(Z \mid Y)=\prod_{i=1}^{d} p\left(Z_{i} \mid Y\right)$ are independent Bernoulli r.v.
- $p(Y \mid Z)=\prod_{i=1}^{d} p\left(Y_{i} \mid Z\right)$ are independent Bernoulli r.v.

However the model encodes non-trivial dependences between the variables $\left(Y_{1}, \ldots, Y_{n}\right)$

## Ising model

Reminder: $X=\left(X_{i}\right)_{i \in V}$ is a vector of random variables, taking value in $\{0,1\}^{|V|}$, whose distribution has the following exponential form:

$$
p(x)=e^{-A(\eta)} \prod_{i \in V} e^{\eta_{i} x_{i}} \prod_{(i, j) \in E} e^{\eta_{i, j} x_{i} x_{j}}
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The associated log-likelihood is this:

$$
\ell(\eta)=\sum_{i \in V} \eta_{i} x_{i}+\sum_{(i, j) \in E} \eta_{i, j} x_{i} x_{j}-A(\eta)
$$

## Hidden Markov Random Field



Segmentation

## Hidden Markov random Field

$$
p(y \mid x)=e^{-A(\eta)} \prod_{i \in V} e^{\left\langle w, x_{i}\right\rangle y_{i}} \prod_{(i, j) \in E} e^{\eta_{i, j} y_{i} y_{j}}
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## References I

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Smolensky, P. (1986). Information processing in dynamical systems: foundations of harmony theory. In Parallel distributed processing: explorations in the microstructure of cognition, vol. 1, pages 194-281. MIT Press.

