

Callisto (ANR-09-CORD-003): Calibration in stereo vision with statistical methods

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Objectives

High precision in early steps of stereo vision pipeline:

- Internal calibration.
- Match points extraction.
- External calibration.
- Stereo rectification of pairs of images.
- Dense matching in pairs of images.
- Merging of 3D point clouds issued from different pairs.
- Vectorization of point cloud to a mesh.
- Mesh refinements, processing, etc.

Techniques

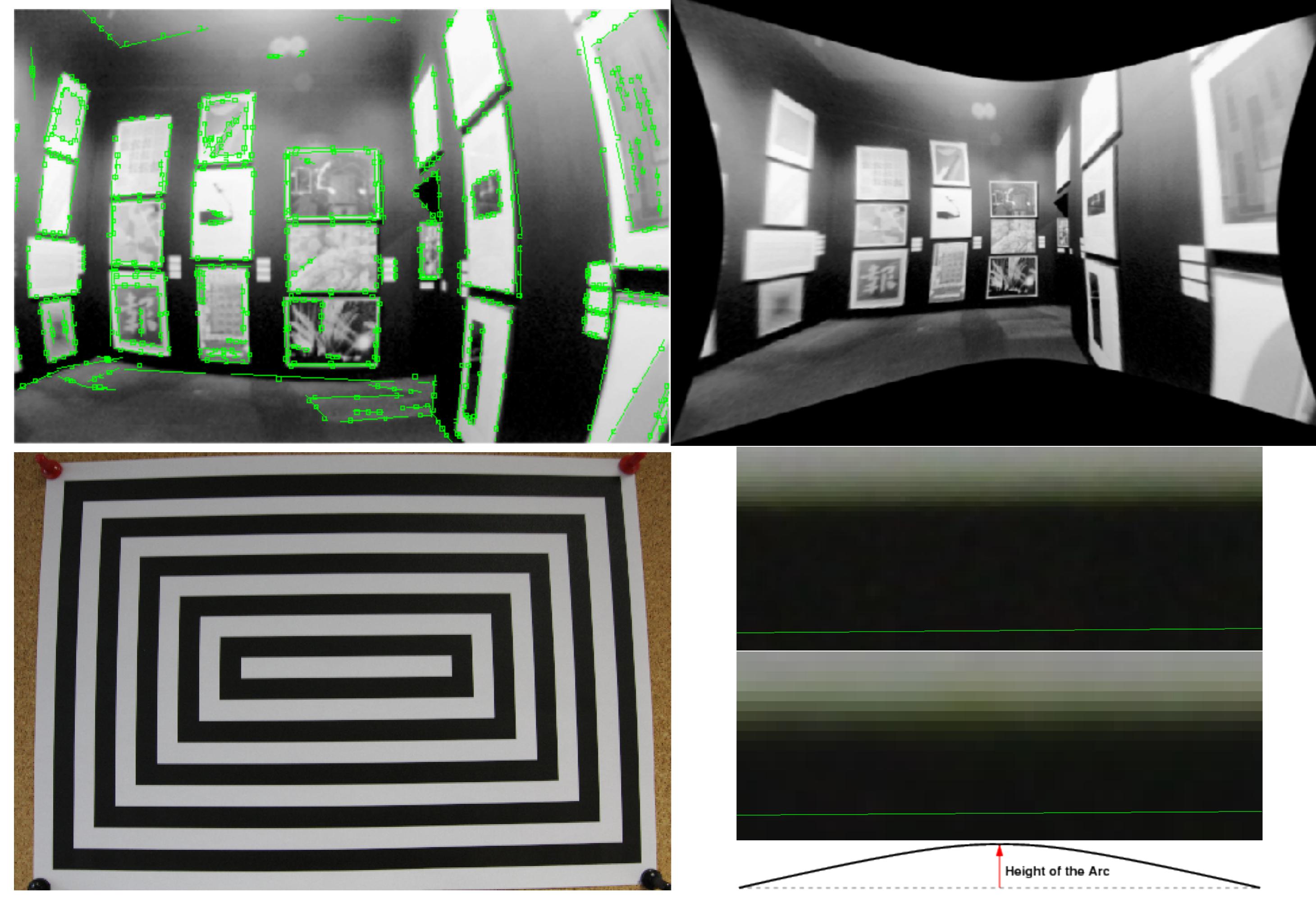
- SIFT and MSER interest points in images
- Global optimization in external calibration
- Statistical methods.
- *a contrario* methodology.
- Control of type I errors (false positives).
- Sparse recovery.
- Randomized estimator (RANSAC).
- False Discovery Rates methods

Selection of model: Epipolar geometry or homography?



Correction of lens distortion

Will be done separately from internal calibration. Goal: achieve at least 1/10th pixel precision: parametric models will probably be inadequate, so we will have to look for a dense correction field.



Deliverables

Milestone	Partner	Date
Website of Callisto project	Imagine	T0+1
Implementation of Martinec's calibration	(T3A)	Imagine T0+3
Short advancement report		Imagine T0+6
Tech. report on <i>distortion correction</i>	(T2A)	CMLA T0+8
Tech. report on <i>keypoint matching</i>	(T1A)	LTCI T0+10
Long advancement report		Imagine T0+12
Tech. report on rotation estimation	(T3B)	Imagine T0+15
Short advancement report		Imagine T0+18
Tech. report on internal parameter estimation	(T2B)	CMLA T0+20
Tech. report: Link <i>a contrario</i> ↔ multiple hypot. test.	(T1B)	Imagine T0+20
Tech. report on MSER	(T1C)	LTCI T0+20
Long advancement report		Imagine T0+24
Tech. report on translation estim.	(T3C)	Imagine T0+28
<i>Online demo.</i> of internal calibration	(T2C)	CMLA T0+30
Short advancement report		Imagine T0+30
Tech. report on RANSAC	(T3D)	Imagine T0+32
<i>Calibration software</i> release in CertisLibs		Imagine T0+36
Final report		Imagine T0+36

Personnel

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