

# Devil: an IDL for Hardware Programming

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# Interfacing Devices ...

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*The Devil is  
in the details*

# Looking into the "Details"

(busmouse.h)

```
#define MSE_DATA_PORT          0x23c
#define MSE_SIGNATURE_PORT      0x23d
#define MSE_CONTROL_PORT        0x23e
...
#define MSE_READ_X_LOW          0x80
#define MSE_READ_X_HIGH         0xa0
```

(busmouse.c)

```
outb(MSE_READ_Y_LOW, MSE_CONTROL_PORT);
dy = (inb(MSE_DATA_PORT) & 0xf);
outb(MSE_READ_Y_HIGH, MSE_CONTROL_PORT);
buttons = inb(MSE_DATA_PORT);
dy |= (buttons & 0xf) << 4;
buttons = ((buttons >> 5) & 0x07);
```

# Assessment of Existing (Linux) Drivers

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- ◆ Assembly-level programming style
- ◆ Macros
  - unreadable code factorized, not suppressed
  - no single programming style
  - no typing / consistency checking

The hardware interface code is:

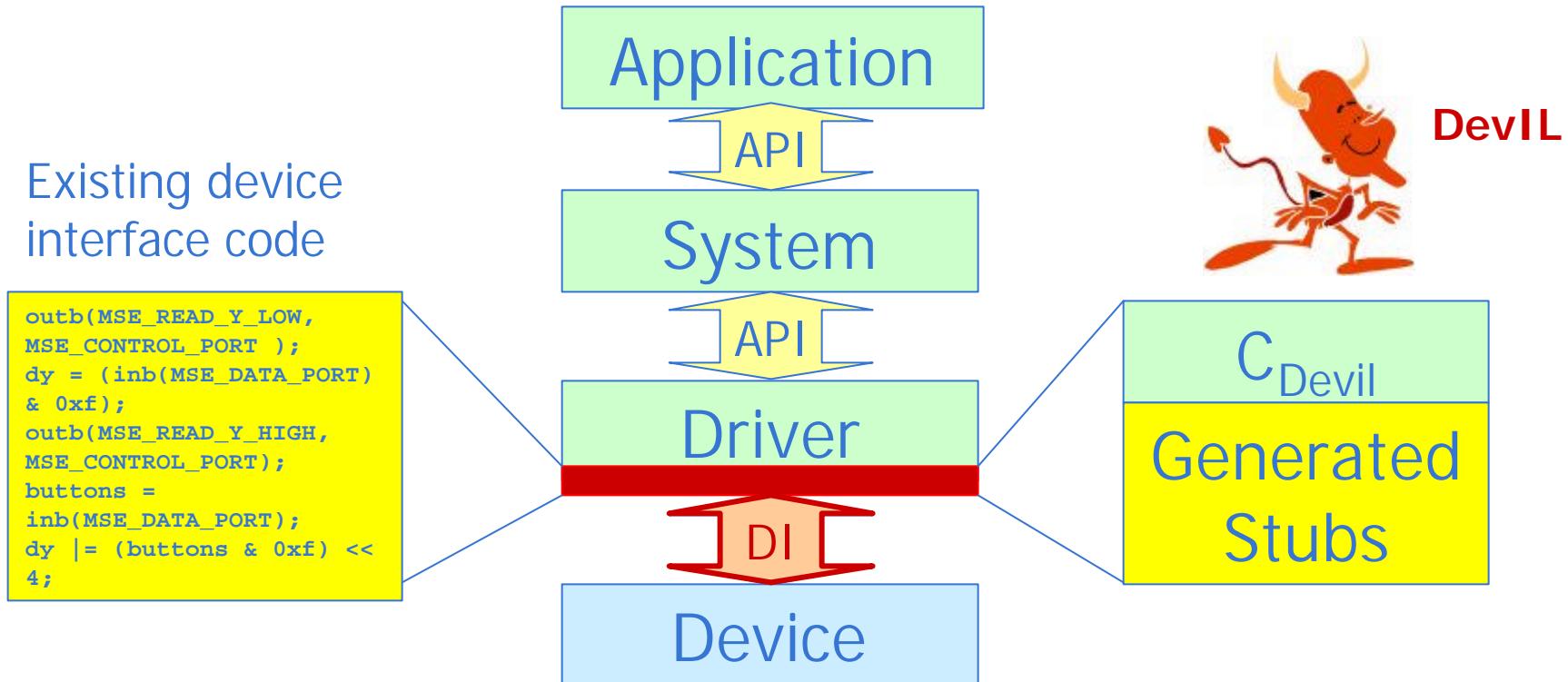
- hard to read and maintain
- tedious and error prone

# Lack of Support for the Driver Programmer

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- ◆ Paper documentation
    - » natural language
    - » manufacturer-specific terminology
    - » inconsistencies, ambiguities, omissions, typos
  - ◆ Mixed levels of abstractions
    - » communication mechanisms, data layout, semantics
  - ◆ Inherent complexity of devices
- Laborious testing until expected functionality is obtained

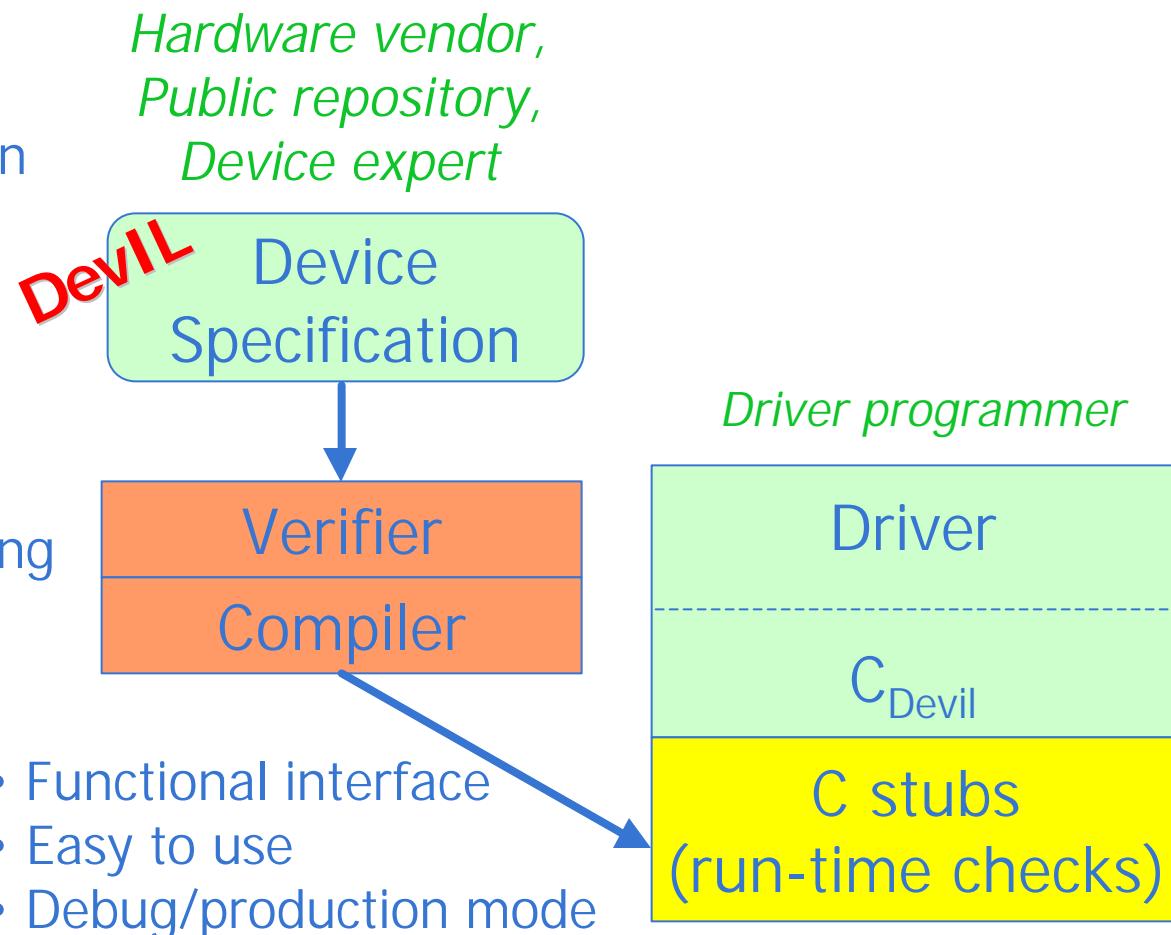
# Devil: a DEVice Interface Language



# Our Vision

- High-level description of device interface
- Easy to write
- Strongly typed

- Consistency checking
- Code generation



# Devil: Key Concepts

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- ◆ Ports
  - communication point, address range
- ◆ Registers
  - repository of data, granule of exchange
- ◆ Variables: programmer interface
  - collection of register fragments
  - semantic values:
    - » bounded integers
    - » enumerated types

# Programmer Support: Verifying Critical Properties

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- ◆ Consistency of Devil specifications
  - no omission
  - no double definition
  - no overlapping
  - type/size of variables
- ◆ C<sub>Devil</sub> interface usage in debug mode
  - compile-time (type checking)
  - run-time (assertion checking)



# The Logitech Busmouse: functional interface

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- ◆ dx (delta X)
  - relative horizontal movement
- ◆ dy (delta Y)
  - relative vertical movement
- ◆ buttons
  - button state

Read only variables !

# Device Interface Code: C<sub>Devil</sub> vs. existing drivers

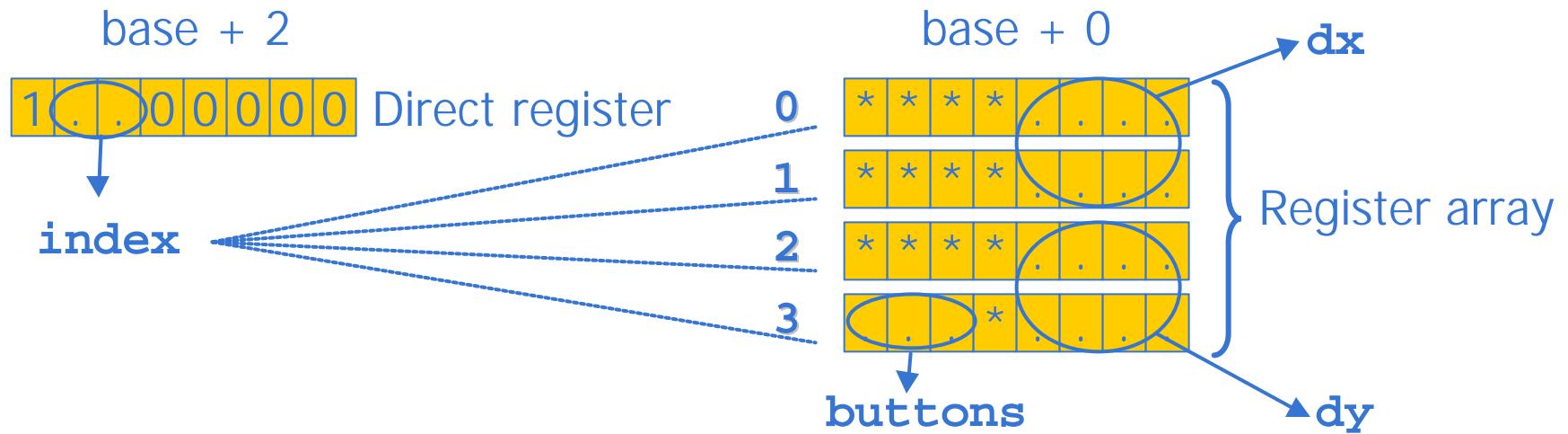
```
dx = get_dx();
dy = get_dy();
buttons = get_buttons();
```

C<sub>Devil</sub>

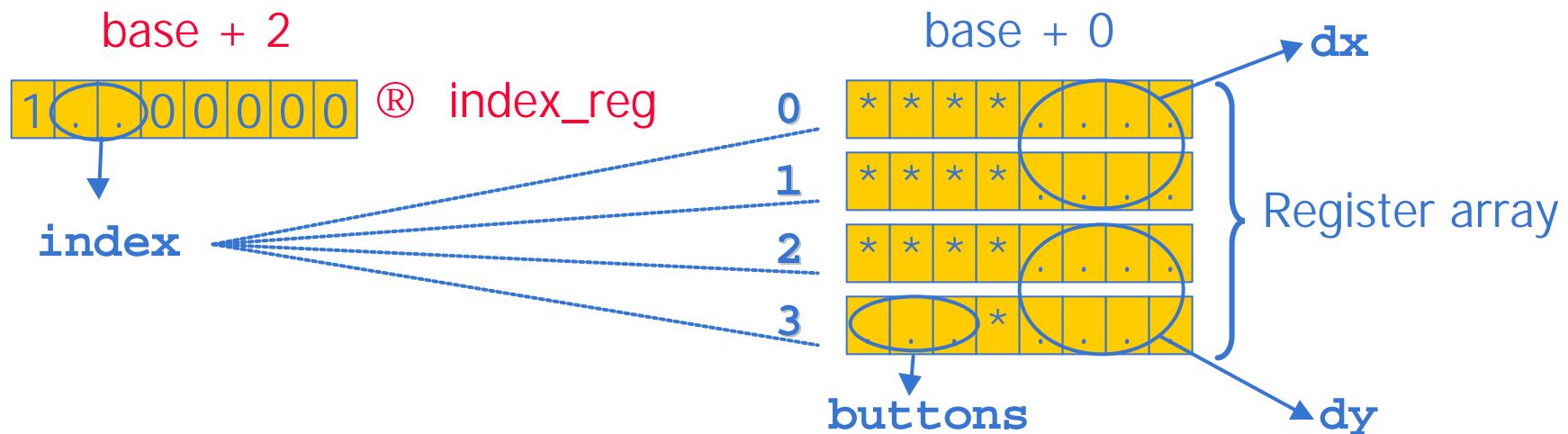
```
outb(MSE_READ_X_LOW, MSE_CONTROL_PORT);
dx = (inb(MSE_DATA_PORT) & 0xf);
outb(MSE_READ_X_HIGH, MSE_CONTROL_PORT);
dx |= (inb(MSE_DATA_PORT) & 0xf) << 4;
outb(MSE_READ_Y_LOW, MSE_CONTROL_PORT );
dy = (inb(MSE_DATA_PORT) & 0xf);
outb(MSE_READ_Y_HIGH, MSE_CONTROL_PORT );
buttons = inb(MSE_DATA_PORT);
dy |= (buttons & 0xf) << 4;
buttons = ((buttons >> 5) & 0x07);
```

Existing  
code

# The Logitech Busmouse: detailed description

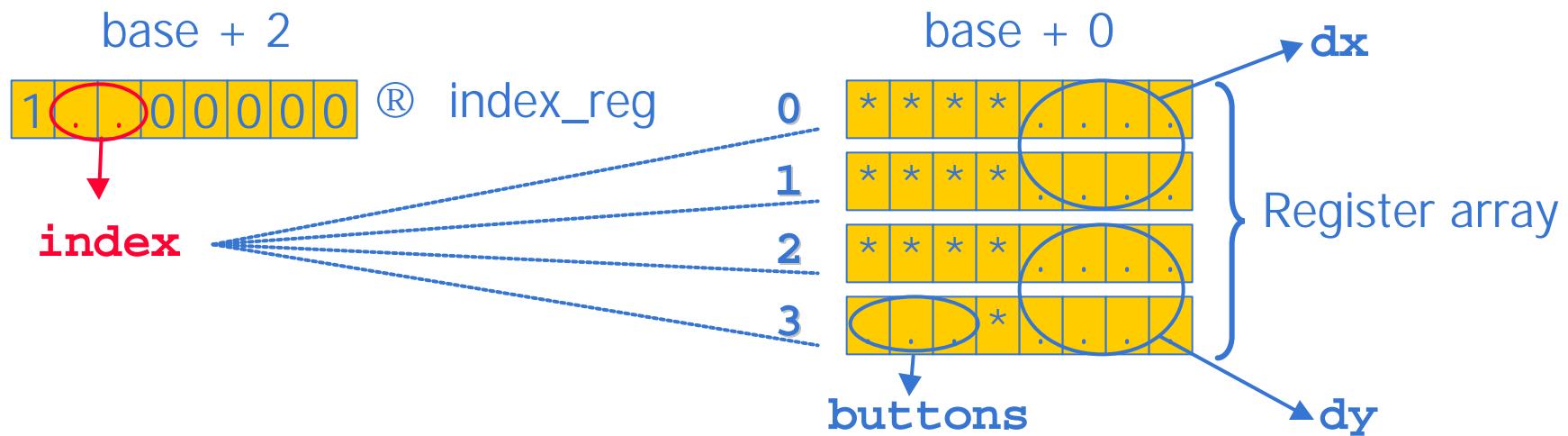


# Direct registers



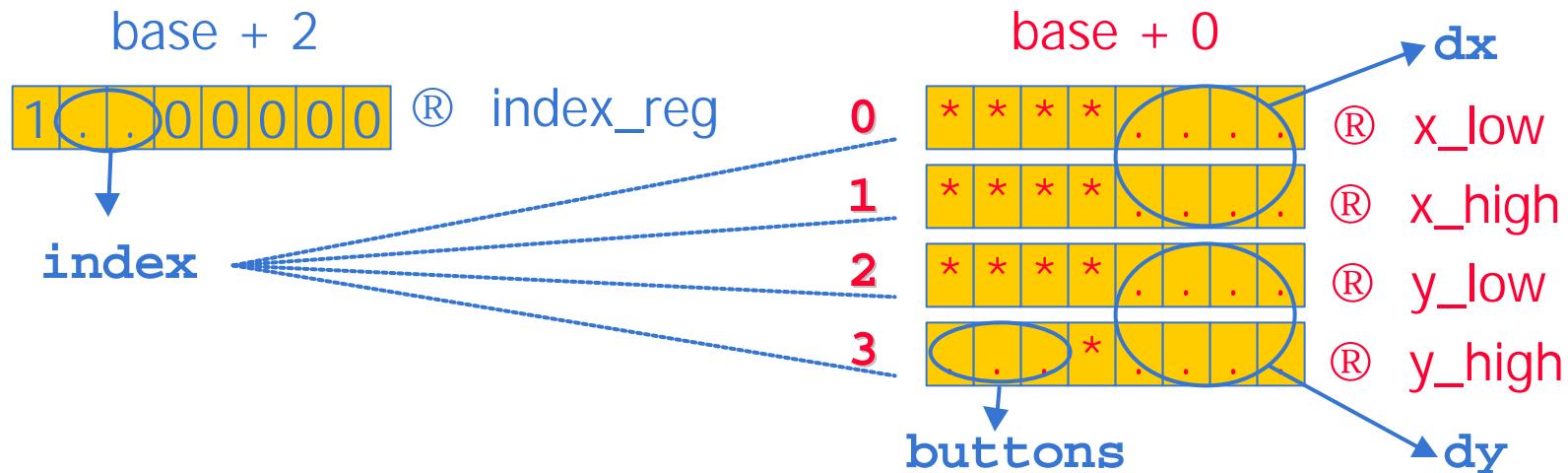
```
...
register index_reg = write base@2,
    mask '1..00000': bit[8];
```

# Private device variables



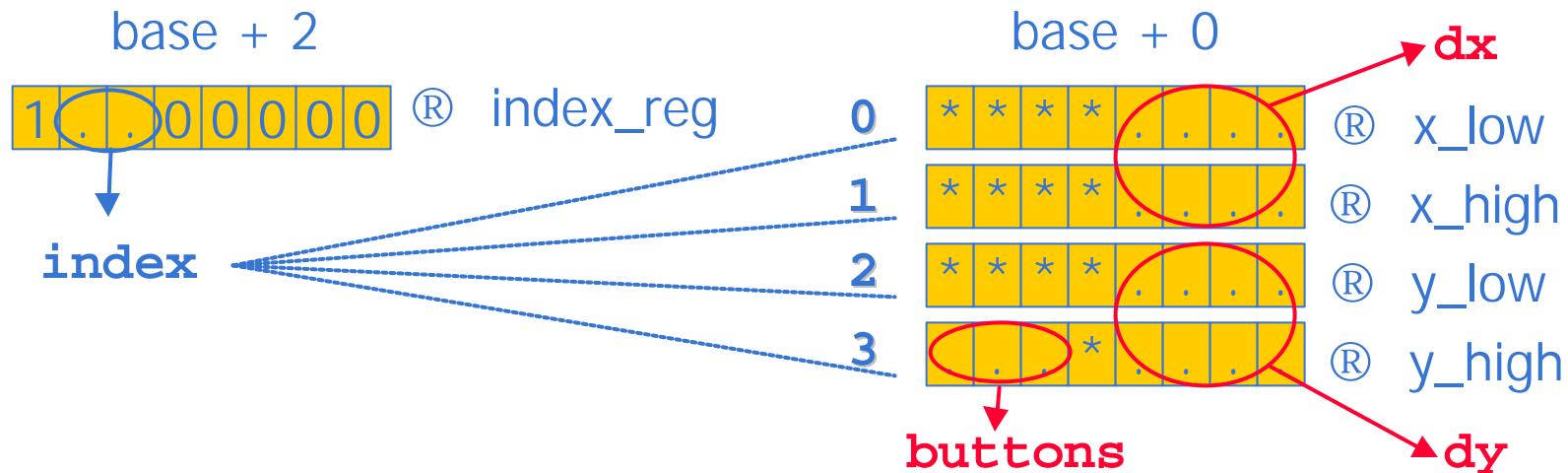
```
...
register index_reg = write base@2, mask '1..00000' : bit[8];
private variable index = index_reg[6..5] : int(2);
```

# Indexed registers



```
...
register index_reg = write base@2, mask '1..00000' : bit[8];
private variable index = index_reg[6..5] : int(2);
...
register x_low  = read base@0, pre {index = 0},
          mask '****....' : bit[8];
register x_high = read base@0, pre {index = 1},
          mask '****....' : bit[8];
...
```

# Interface variables



```
...
register index_reg = write base@2, mask '1..000000' : bit[8];
private variable index = index_reg[6..5] : int(2);
...
register x_low  = read base@0, pre {index = 0}, mask '*****....' : bit[8];
register x_high = read base@0, pre {index = 1}, mask '*****....' : bit[8];
...
variable dx = x_high[3..0] # x_low[3..0],
          volatile : signed int(8);
variable dy = y_high[3..0] # y_low[3..0],
          volatile : signed int(8);
```

# What About Performance ?

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- ◆ Sharing registers between variables may induce performance penalty
  - additional I/O w.r.t. hand-crafted drivers
  - command parameters
- ◆ Re-engineering of performance critical drivers
  - IDE disk driver
  - Permedia2 X11 driver

# IDE Linux Driver (intel 82371SB)

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- ◆ Characteristics:

- many initializations
  - DMA/PIO-loop for transfer

- ◆ DMA mode

C: 14 I/Os	Devil: 20 I/Os	14.25 Mb/s
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- ◆ PIO-32bits mode, 16 sectors/interrupt

C (rep loop):	8.17 Mb/s
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Devil (C loop):	7.36 Mb/s (90% of C)
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Devil (rep loop):	8.17 Mb/s
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# Permedia2 X11 driver

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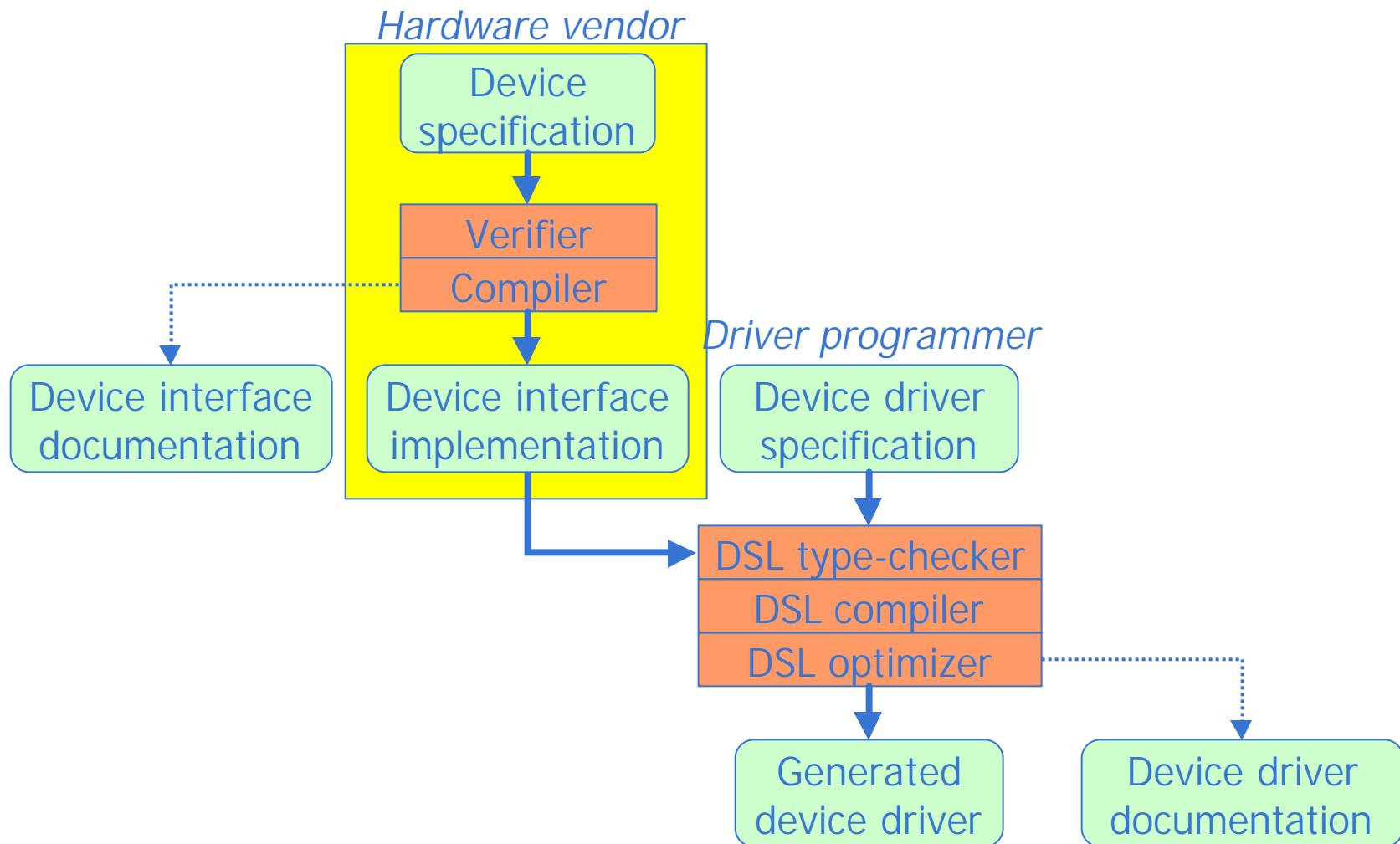
- ◆ Characteristics:
  - registers mapped in memory
  - buffered write (on-chip FIFO)
  - same number of I/Os
- ◆ Screen copy operations (24 bpp)
  - 100% performance of C
- ◆ Rectangle operations (24 bpp)
  - 97%-100% performance of C
  - difference due to stub code for small size operation

# Benefits of Devil

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- ◆ Expressivity
  - » advanced Devil constructs (see paper and manual)
  - » DMA, sound, interrupt, Ethernet controllers
- ◆ Guaranteed safety
  - » Mutation-based experiment (typo simulation)
  - » 5 times less prone to errors than C code
- ◆ Negligible performance overhead
- ◆ Improved productivity
  - » reuse of specifications
  - » tools and verifications

# Our Vision (On-going work)



# Conclusion

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- ◆ Step toward the development of robust drivers
- ◆ Compiler/checker available
- ◆ No performance penalty
- ◆ Expressive enough to allow the specification of various devices

Instance of our vision: “DSL for Operating System Design”

The details are in Devil



# Questions ?

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- ◆ Specifications/compiler/manual available :  
[www.irisa.fr/compose/devil](http://www.irisa.fr/compose/devil)
- ◆ Public CVS repository of specs  
Please contribute ...